Interpretability of Unsupervised Anomaly Detection Model: One-Class Support Vector Machine with Rule Extraction

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1. Introduction

Nuclear Power Plants (NPPs) are safety-critical facilities, and minimizing human errors during operation is essential for maintaining safety. Accordingly, many studies are being conducted to reduce human errors. Among them, Artificial Intelligence (AI)-based decision support systems are being researched to minimize human errors by operators. However, the black-box characteristics of AI need to be addressed before these studies can be applied in the field.

Recently, eXplainable AI (XAI) methods have been developed to address the black-box characteristics of AI systems. The XAI methods can provide users with an explanation of why the AI's output values were derived. These XAI methods are being applied to AI-based decision support systems to reduce human error in NPPs. AI-based decision support systems are categorized into supervised learning-based classification and regression problems, as well as unsupervised learning-based anomaly detection. The application of XAI to supervised learning-based models is an active area of research. On the other hand, the application of XAI to unsupervised learning-based AI models is still limited. Therefore, this study utilizes the One-Class Support Vector Machine (OCSVM) with rule extraction method. It combines OCSVM, an unsupervised learning-based AI method, and rule extraction method, an XAI method. As part of the primary research to evaluate the applicability of the OCSVM with rule extraction, two case studies are conducted as follows:

- (1) Anomaly detection using accelerated aging data of Insulated Gate Bipolar Transistor (IGBT)
- (2) Anomaly detection using NPP simulation data

The IGBT data are sourced from open-source data provided by the National Aeronautics and Space Administration (NASA), and NPP simulation data are collected using a Compact Nuclear Simulator (CNS). An anomaly detection model is developed and evaluated in the case study using the OCSVM method. Additionally, rule extraction is performed based on the pre-trained anomaly detection model. The extracted rules can identify the logical structure of OCSVM (e.g., the boundary of the normal region can be identified as the rules). Consequently, it is expected to be a useful tool to enhance the interpretability of OCSVM-based anomaly detection models.

2. Methods

This section introduces OCSVM and rule extraction and describes the method that combines them, known as OCSVM with rule extraction.

2.1 OCSVM

The OCSVM method [1] is derived from traditional SVM method. The SVM method is a supervised learning algorithm primarily utilized for classification and regression problems. As a supervised learning algorithm, it necessitates a labeled dataset. Additionally, it employs a kernel function to transform the data into a high-dimensional feature space. This enables it to solve non-linear problems and facilitates the recognition of relationships between the data. The primary goal of the SVM method is to establish a decision boundary between datasets. Fig. 1 illustrates the hyperplane and the line with support vectors separating two datasets (i.e., '+' and '-'). Here, the greater the distance between the hyperplane and the line with support vectors, the higher the confidence level, indicating that training progresses toward enlarging the margin.



Fig. 1. SVM configuration; hyperplane, line with support vectors, and margin.

The OCSVM method is trained similarly to the SVM method. However, the OCSVM method differs because it is an unsupervised learning algorithm. This means that unlabeled data are used; thus, the margin between the data is not utilized, as depicted in Fig. 1. In the OCSVM

method, the margin is the distance between the origin and the hyperplane, as depicted in Fig. 2; similarly to the SVM method, training aims to maximize the margin.



Fig. 2. OCSVM configuration; hyperplane, and margin.

The primary hyper-parameters of the OCSVM method are v and γ . v represents the upper bound on the learning error rate and the lower bound on the support vector rate (which primarily determines the anomaly detection boundary). γ is the coefficient for the radial basis function kernel, influencing the curvature of the decision boundary. The complexity of the algorithm increases as both hyper-parameter values increase, so it is crucial to find the parameter values that optimized performance.

2.2 OCSVM with rule extraction

The rule extraction method [2] employs a clustering algorithm to generate a hypercube. The hypercube represents boundary regions in a multi-dimensional feature space. The implementation of this hypercube involves the following steps:

- (1) Obtaining clustering results:
 - Clustering algorithms such as k-means and kprototypes are employed to group the data into clusters, utilizing the outcomes of the OCSVMbased anomaly detection model.
- (2) Finding the boundary points of each cluster:
 - To determine the boundaries of each cluster, certain data points belonging to that cluster are selected.
 - The minimum and maximum values of the selected data points define the boundaries, and this process is repeated for each variable.
- (3) Constructing a hypercube in a multi-dimensional feature space:
 - Combining the ranges for each variable to create a hypercube.
- (4) Verifying the hypercube boundaries:

- Verify if outliers exist within the hypercube and repeat the hypercube creation process until no outliers are present.

The boundary conditions of these hypercubes serve as rules. In other words, the boundary conditions of the OCSVM-based anomaly detection model can be articulated as rules.

3. Data Preparation

This section describes the datasets used in the case study and discusses data standardization.

3.1 IGBT accelerated aging data

The data on accelerated aging of IGBTs are obtained from open-source data [3]. The IGBT data were subjected to accelerated aging by applying temperature and voltage conditions higher than the design characteristics. As the IGBT ages, it will fail, with the failure symptom being latch-up. Latch-up causes a low output voltage relative to the supply voltage, as shown in Fig. 3. The difference between the supply and output voltage is defined as the degradation characteristic. The failure criterion is the point where the output voltage drops sharply. The IGBT datasets include information for 4 devices, experimental temperature and voltage, and degradation characteristics. For anomaly detection model development, we only use operation time, temperature, and voltage. The other variables, including degradation characteristics, are not available in the field and are therefore excluded from the AI model development. Additionally, we used normal condition data for 3 devices to train the anomaly detection model. The normal condition data for the remaining 1 device and all anomaly data were used for validation.



Fig. 3. Degradation characteristic of IGBT data; note the low output voltage (blue line) relative to the supply voltage (orange line).

3.2 NPP simulation data

The NPP simulation data were collected using the CNS. The collected data were divided into normal operating data for training the anomaly detection model and abnormal operating data for validation. Loss of coolant accident and steam generator tube rupture scenarios are utilized for the abnormal operating data. Similar to the IGBT dataset, only the normal operating data are used for training. The validation and test data utilize a subset of the normal operating data. 137 variables were selected as input for the AI based on the symptom requirements of each scenario.

3.3 Data standardization

Data standardization is a scaling method that makes the mean 0 and the variance 1 for each variable; that is, the values are transformed to have a Gaussian normal distribution. This is expressed as in Eq. (1).

$$x' = \frac{x - mean(x)}{std(x)} \tag{1}$$

This not only prevents learning from being dependent on the magnitude of the variable values, but also contributes to faster learning.

4. Case Study

This section discusses a series of case studies that utilize the OCSVM method to develop anomaly detection models and then extract rules. The used data are IGBT data and NPP simulation data.

4.1 Development of anomaly detection model and rule extraction using IGBT data

An anomaly detection model is developed and optimized using the IGBT data. Then, based on the pretrained anomaly detection model, rules are extracted using a rule extraction method. The training data are normal data for 3 devices, as described earlier. The validation and test data consist of normal and anomaly for the remaining 1 device. A grid search algorithm is utilized, and the v and γ values are optimized. The optimized model is selected based on three metrics calculated using the values (i.e., TP, FP, FN, TN) from Table I.

Table I: Confusion Matrix for Anomaly Detection Model Evaluation

	Expected		
Predicted		Normal	Abnormal
	Normal	TP	FP
	Abnormal	FN	TN

The optimization criteria are based on the following evaluation metrics:

(1) Metric 1: percentage of samples predicted to be normal that are actually normal (for training data; normal data only) (refer to Eq. (2))

$$Metric1 = \frac{TP}{TP+FP} \text{ for training data}$$
(2)

(2) Metric 2: percentage of samples predicted to be normal that are actually normal (for validation data; normal data only) (refer to Eq. (3))

$$Metric2 = \frac{TP}{TP+FP}$$
 for validation data (3)

(3) Metric 3: percentage of samples predicted to be abnormal that are actually abnormal (for validation data; abnormal data only) (refer to Eq. (4))

$$Metric3 = \frac{TN}{TN + FN}$$
 for validation data (4)

The highest performance is observed for the hyperparameter condition with v = 0.1 and $\gamma = 0.4$; the performance percentages for each metric are 90.57% (metric 1), 96.9% (metric 2), and 100% (metric 3). The results obtained through rule extraction based on the optimized model are shown below, with 9 rules were extracted. The rules are divided into the ranges of the input variables, such as time (operation time), temperature, and voltage.

- (1) (62 \leq time \leq 784) and (100 \leq temperature \leq 240) and (2.5 \leq voltage \leq 4.5)
- (2) (902 \leq time \leq 1504) and (265 \leq temperature \leq 280) and (5 \leq voltage \leq 5.5)
- (3) (600 \leq time \leq 1085) and (240 \leq temperature \leq 265) and (voltage = 5)
- (4) $(2280 \le \text{time} \le 2281)$ and (temperature = 100) and (voltage = 5.5)
- (5) $(1440 \le \text{time} \le 1805)$ and $(265 \le \text{temperature} \le 280)$ and $(5 \le \text{voltage} \le 6)$
- (6) $(1861 \le \text{time} \le 1924)$ and (temperature = 280) and (voltage = 6)
- (7) (1800 \leq time \leq 1985) and (265 \leq temperature \leq 280) and (voltage = 5.5)
- (8) $2041 \le \text{time} \le 2223$) and (temperature = 265) and (voltage = 5.5)
- (9) $(2042 \le \text{time} \le 2105)$ and (temperature = 280) and (voltage = 5.5)

4.2 Development of anomaly detection model and rule extraction using CNS data

An anomaly detection model is developed and optimized using CNS data. Similarly to the IGBT data, rules are extracted based on a pre-trained model. The data were split into normal and abnormal data, as described in subsection 3.2, to serve as training, validation, and test data. The performance of the anomaly detection model using CNS data is as follows: 95.12% (metric 1), 97.35% (metric 2), and 99.6% (metric 3). The hyper-parameters are v = 0.1 and $\gamma = 0.6$. The extracted rules based on the optimized model are shown in Fig. 4. All 137 variables are used as building blocks for the rules. As a result, 86 rules were extracted.



Fig. 4. A portion of the rule extraction results from the CNS data-based anomaly detection.

5. Conclusion

AI-based decision support systems are actively being researched to reduce human error in the operation of NPPs. However, the black-box characteristics of AI can be an obstacle to the practical application of such research. Recently, XAI methods have been applied to solve this problem. However, most XAI applications are limited to supervised learning-based algorithms. However, many researchers are also developing anomaly detection models using unsupervised learning algorithms. Therefore, applying XAI methods to unsupervised learning algorithms is necessary.

In this study, we consider the applicability of the OCSVM with rule extraction method, which combines the OCSVM method, an unsupervised learning algorithm, with the rule extraction method, an XAI algorithm. The case studies were performed to assess

the applicability of: (1) anomaly detection using accelerated aging data of IGBT and (2) anomaly detection using NPP simulation data. The extracted rules reveal the logical structure of the OCSVM method-based anomaly detection models. These results are expected to enhance the interpretability of unsupervised learning-based anomaly detection models. However, a limitation exists: each input variable contributes to a rule, potentially complicating interpretation as the number of variables increases. This limitation is difficult to address because we ultimately extract rules based on the characteristics of the OCSVM model. In future work, we plan to explore other AI models or supplement the rule reduction technique to better reflect the characteristics of the data and derive interpretable rules.

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