





Abstract

When the molten corium relocates into the lower plenum, a gap is expected to be formed due to the wall roughness, a large temperature difference and the strong vaporization of trapped water in a small gap between the debris and the wall. If the gap exists, this gap can play an important role in preventing the temperature increase of the debris and the wall based on this new gap cooling

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mechanism. At present, MELCOR1.8.4 does not consider these gap-cooling phenomena. Therefore a conceptual gap-cooling model has been developed and implemented into the lower plenum model in MELCOR to take into account the gap effect in the lower plenum The LAVA-4 experimental data were analyzed by using MELCOR with and without "gap model". When the "gap model" is implemented, the peak temperature of the vessel wall was reduced and its cooling rate was increased. But the rapid cool-down rate after peak temperature was not estimated properly. The current "gap model" does not have a model to simulate the phenomena such as limitation of water ingression into the gap due to rapid steam generation and the effect from gap size change. Also the heat transfer coefficients used in the model should be supplied by the user. These limitations will be studied further to develop a more analytical model.



debris

Monde [4] . 가 LAVA-4 . **II**

II.1 MELCOR

MELCOR COR (; 1, 3, 1, debris 1), , , ,

[5,6].

MELCOR1.8.4 (Gap Cooling Phenomena)

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 $\begin{array}{lll} \text{debris} & : & C_{p,d}(T_d^n - T_d^o) = (q_s - q_{d,h} - q_{d,v} - q_{d,d}) \Delta t \\ & : & C_{p,h,n}(T_{h,n}^n - T_{h,n}^o) = (q_{n-1,n} + q_{d,h} - q_{hv}) \Delta t \\ & : & C_{p,h,i}(T_{h,i}^n - T_{h,i}^o) = (q_{i-1,i} - q_{i,i+1}) \Delta t \\ & : & C_{p,h,1}(T_{h,1}^n - T_{h,1}^o) = (-q_{h,c} - q_{1,2}) \Delta t \end{array}$

 $M_{d}^{}\ast c_{p,d}^{}$ Cp,d d LAVA-4 s debris . debris, h . d , i , n , v , 1 cavity , c debris . q_{dh} . , q_{dv} debris , q_{dd} debris cell , . q_{n-1,n} n-1 n i , $q_{i-1,i}$ $\mathbf{q}_{i,i+1}$ cavity . $q_{\rm hc}$, q_{12} (1) •

LAVA-4





 $\begin{array}{cccc} h_{dw} & debris & , A_d & ring \\ debris & , h_{gap} & , T_w \\ . & debris \\ \hline \end{array} \begin{array}{c} & & & \\$

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(: $\varepsilon\sigma(T_s^2+T^2sat)(Ts+Tsat)$

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 \mathbf{q}_{dh}

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 h_{hw} , A_h ring debris . debris , , . . 7



debris

 q_{dw}, q_{hw} Monde

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$$q_{dw} \triangleq h_{dw} A_{d} (T_{d}^{n} - T_{w})$$

$$q_{hw} \triangleq h_{hw} A_{h} (T_{h,n}^{n} - T_{w})$$

$$q(Monde) = C h_{fg} \sqrt{\boldsymbol{r}_{g}} \sqrt[4]{\boldsymbol{g}\boldsymbol{s}(\boldsymbol{r}_{f} - \boldsymbol{r}_{g})}$$

$$C = 0.16 \left[1 + 6.7 * 10^{-4} \left(\frac{\boldsymbol{r}_{f}}{\boldsymbol{r}_{g}} \right)^{0.6} \left(\frac{\lambda_{gap}}{\boldsymbol{d}} \right) \right]^{-1}$$

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debris

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$$q_{dw} = \frac{q_{dw}}{q_{dw} + q_{hw}} * q(Monde)$$
$$q_{hw} = \frac{q_{hw}}{q_{dw} + q_{hw}} * q(Monde)$$

 $\boldsymbol{q}_{\text{dh}}$

$$\frac{\text{debris}}{C_{p,d}(T_d^n - T_d^o)} = \left[q_s - h_{gap}A_d(T_d^n - T_{h,n}^n) - q_{dw} - q_{d,d} - q_{d,v}\right]\Delta t$$
$$\Rightarrow -h_{gap}A_d\Delta t * T_{h,n}^n + (C_{p,d} + h_{gap}A_d\Delta t + h_{dw}A_d\Delta t) * T_d^n$$
$$= C_{p,d}T_d^o + (q_s + h_{dw}A_dT_w - q_{d,d} - q_{d,v})\Delta t$$

$$C_{p,h,n} (T_{h,n}^{n} - T_{h,n}^{o}) = \left[q_{n-1,n} + h_{gap} A_{d} (T_{d}^{n} - T_{h,n}^{n}) - q_{hw} - q_{h,v} \right] \Delta t$$

$$\Rightarrow -\frac{A_{h} K_{n}}{\Delta Z_{n-1}} \Delta t T_{h,n-1}^{n} + (C_{p,h,n} + \frac{A_{h} K_{n}}{\Delta Z_{n-1}} \Delta t + h_{hw} A_{h} \Delta t + h_{gap} A_{d} \Delta t) T_{h,n}^{n} - h_{gap} A_{d} \Delta t T_{d}^{n}$$

$$= C_{p,h,n} T_{h,n}^{o} + h_{hw} A_{h} T_{w} \Delta t - q_{d,v} \Delta t$$

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Thomas algorithm[8]

$$\stackrel{\rho}{A} \bullet \stackrel{\rho}{X} = \stackrel{\rho}{B}$$

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debris

$$\begin{aligned} \mathbf{A}_{n,n-1} &= -\frac{\mathbf{A}_{h}\mathbf{K}_{n}}{\Delta \mathbf{Z}_{n-1}}\Delta t \\ \mathbf{A}_{n,n} &= \mathbf{C}_{p,h,n} + \frac{\mathbf{A}_{h}\mathbf{K}_{n}}{\Delta \mathbf{Z}_{n-1}}\Delta t + \mathbf{h}_{gap}\mathbf{A}_{d}\Delta t + \mathbf{h}_{hw}\mathbf{A}_{h}\Delta t \\ \mathbf{A}_{n,n+1} &= -\mathbf{h}_{gap}\mathbf{A}_{d}\Delta t \\ \mathbf{b}_{n} &= \mathbf{C}_{p,h,n}\mathbf{T}_{h,n}^{o} + \mathbf{h}_{hw}\mathbf{A}_{h}\mathbf{T}_{w}\Delta t - \mathbf{q}_{d,v}\Delta t \end{aligned}$$

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$$A_{n+1,n} = -h_{gap}A_{d}\Delta t$$

$$A_{n+1,n+1} = C_{p,d} + h_{gap}A_{d}\Delta t + h_{dw}A_{d}\Delta t$$

$$b_{n+1} = C_{p,d}T_{d}^{o} + (q_{s} + h_{dw}A_{d}T_{w} - q_{dd} - q_{dv})\Delta t$$

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그림 1 LAVA-4 실험 경우 반구 외벽 온도



그림 2 LAVA-4 실혁 경우 상부 debris 온도