

## One-Node Solution Based Nonlinear Analytic Nodal Method

150

MASTER

( 15%) 가 ,

### Abstract

As a replacement of the two-node nodal formulation to solve the transverse-integrated neutron diffusion equation, which was conventionally used in the implementation of the nonlinear nodal method, a one-node nodal formulation is derived. In order to achieve better convergence property, the two one-dimensional neutron diffusion equations on the radial domain are solved simultaneously. The boundary conditions used for the one-node problem are taken from the incoming partial currents specified at the four boundary surfaces and the outgoing partial currents are solved for. The one-node based nodal solution is easy to apply within the framework of the coarse mesh finite difference method with any kind of symmetry option. The proposed method was implemented in the MASTER code and the results obtained from the applications

to steady-state and transient calculations indicate that the number of nodal updates increases slightly (about 15%) compared to the two-node formulation, but the total computation time remains essentially unchanged.

1.

(Coarse Mesh Finite Difference, CMFD)

CMFD

(Analytic Function Expansion Nodal, AFEN)

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[1], Chao

CMFD

[2]. CMFD

ANM(Analytic Nodal Method) AFEN

CMFD

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( 3 , x,y,z 3 )

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CMFD

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CMFD

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2.

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3

$h$

2.1

x-y

2

$$-D \frac{d^2}{du^2} \mathbf{f}_u(u) + A \mathbf{f}_u(u) = -L_{\bar{u}}(u) - L_z(u), \quad u \in \{x, y\}, \quad \bar{u} = \begin{cases} y & \text{if } u = x \\ x & \text{if } u = y \end{cases}. \quad (1)$$

$$D = \begin{bmatrix} D_1 & \\ & D_2 \end{bmatrix}, \quad A = \begin{bmatrix} \Sigma_{r1} - \mathbf{1}n\Sigma_{f1} & -\mathbf{1}n\Sigma_{f2} \\ -\Sigma_{l2} & \Sigma_{r2} \end{bmatrix}, \quad \mathbf{1} = \frac{1}{k_{eff}}, \quad (2)$$

$$\mathbf{f}(u) = \begin{bmatrix} \mathbf{f}_1(u) \\ \mathbf{f}_2(u) \end{bmatrix}, \quad L_d(u) = \begin{bmatrix} L_{d1}(u) \\ L_{d2}(u) \end{bmatrix}. \quad (3)$$

(1)

$$L_{\bar{u}}(u) + L_z(u) = \bar{L}_{\bar{u}} + \bar{L}_z + b_1^u \mathbf{x} + b_2^u f_2(\mathbf{x}) \quad , \quad \mathbf{x} = \frac{u}{h}, \quad f_2(\mathbf{x}) = 3\mathbf{x}^2 - \frac{1}{4}. \quad (4)$$

$\bar{L}_z$

$\bar{L}_z$

$\bar{L}_{\bar{u}}$

$$\bar{L}_u = \frac{J_u^r - J_u^l}{h}, \quad J_u^{r,l} = -D \frac{d\mathbf{f}_u}{du} \Big|_{u=\frac{h}{2}, -\frac{h}{2}} \quad (5)$$

(5)

$x \quad y$

$2 \quad 2$

$$\begin{aligned} -D \frac{d^2}{dx^2} \mathbf{f}_x(x) + A \mathbf{f}_x(x) &= -\frac{J_y^r - J_y^l}{h} - \bar{L}_z + b_1 \frac{x}{h} + b_2 \left( 3 \frac{x^2}{h^2} - \frac{1}{4} \right) \\ -D \frac{d^2}{dy^2} \mathbf{f}_y(y) + A \mathbf{f}_y(y) &= -\frac{J_x^r - J_x^l}{h} - \bar{L}_z + b_1 \frac{y}{h} + b_2 \left( 3 \frac{y^2}{h^2} - \frac{1}{4} \right) \end{aligned} \quad (7)$$

(7) 가

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$$J_{ul}^{in} = \frac{1}{4} \mathbf{f}_u \left( -\frac{h}{2} \right) + \frac{1}{2} J_u^l, \quad J_{ur}^{in} = \frac{1}{4} \mathbf{f}_u \left( \frac{h}{2} \right) - \frac{1}{2} J_u^r \quad (8)$$

## 2.2

(7)

$x$

$x$

가

3

(7)

가

$$\mathbf{f}_u(u) = \begin{bmatrix} \mathbf{f}_{u1}(u) \\ \mathbf{f}_{u2}(u) \end{bmatrix} = \begin{bmatrix} r & s \\ 1 & 1 \end{bmatrix} \begin{bmatrix} a_{u1} \sin(\mathbf{k}u) + a_{u2} \cos(\mathbf{k}u) \\ a_{u3} \sinh(\mathbf{m}u) + a_{u4} \cosh(\mathbf{m}u) \end{bmatrix} + \begin{bmatrix} a_{01}^u \\ a_{02}^u \end{bmatrix} + A^{-1} \left( b_1^u \frac{u}{h} + b_2^u f_2 \left( \frac{u}{h} \right) \right) \quad (9)$$

$$\begin{pmatrix} \sinh \\ \cosh \end{pmatrix} \quad (9)$$

$$(7)$$

$$(9) \quad \frac{1}{4} \left( \frac{1}{6} \int_{-h/2}^{h/2} \mathbf{f}_x(x) dx + \frac{1}{6} \int_{-h/2}^{h/2} \mathbf{f}_y(y) dy \right) \quad (8)$$

$$\bar{\mathbf{f}}_x = \bar{\mathbf{f}}_y = \bar{\mathbf{f}} \rightarrow \frac{1}{h} \int_{-h/2}^{h/2} \mathbf{f}_x(x) dx = \frac{1}{h} \int_{-h/2}^{h/2} \mathbf{f}_y(y) dy. \quad (10)$$

$$\frac{1}{h} (J_x^r - J_x^l + J_y^r - J_y^l) + A \bar{\mathbf{f}} = -\bar{L}_z. \quad (11)$$

### 2.3

$$(9) \quad (10)$$

$$\bar{\mathbf{f}}_x - \bar{\mathbf{f}}_y = f_{\text{avg}}(a_{01}^x, a_{02}^x, a_2^x, a_4^x, a_{01}^y, a_{02}^y, a_2^y, a_4^y) = 0 \quad (12)$$

$$\text{가} \quad (11) \quad (9) \quad 2$$

$$f_{NB}(a_{01}^x, a_{02}^x, a_2^x, a_4^x, a_{01}^y, a_{02}^y, a_2^y, a_4^y) = -\bar{L}_z. \quad (13)$$

$$(12) \quad (13) \quad (12), (13)$$

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$$\begin{bmatrix} a_{01}^x \\ a_{02}^x \\ a_{01}^y \\ a_{02}^y \end{bmatrix} = \begin{bmatrix} \mathbf{w}_1 & \mathbf{w}_2 & \mathbf{w}_3 & \mathbf{w}_4 \\ \mathbf{w}_5 & \mathbf{w}_6 & \mathbf{w}_7 & \mathbf{w}_8 \\ \mathbf{w}_3 & \mathbf{w}_4 & \mathbf{w}_1 & \mathbf{w}_2 \\ \mathbf{w}_7 & \mathbf{w}_8 & \mathbf{w}_5 & \mathbf{w}_6 \end{bmatrix} \begin{bmatrix} a_2^x \\ a_4^x \\ a_2^y \\ a_4^y \end{bmatrix} + \begin{bmatrix} \mathbf{w}_{01} \\ \mathbf{w}_{02} \\ \mathbf{w}_{01} \\ \mathbf{w}_{02} \end{bmatrix}. \quad (14)$$

$$(14) \quad (9)$$

2 , 8 . 8

2x2

$$\begin{bmatrix} \mathbf{g}_1 & \mathbf{g}_2 \\ \mathbf{g}_3 & \mathbf{g}_4 \end{bmatrix} \begin{bmatrix} a_1^u \\ a_3^u \end{bmatrix} = \begin{bmatrix} J_{ur1}^{in} - J_{ul1}^{in} \\ J_{ur2}^{in} - J_{ul2}^{in} \end{bmatrix} + \begin{bmatrix} f_{b1}(b_{11}^u) \\ f_{b1}(b_{12}^u) \end{bmatrix}. \quad (15)$$

가

$$\begin{bmatrix} \mathbf{w}_9 & \mathbf{w}_{10} & \mathbf{w}_3 & \mathbf{w}_4 \\ \mathbf{w}_{11} & \mathbf{w}_{12} & \mathbf{w}_7 & \mathbf{w}_8 \\ \mathbf{w}_3 & \mathbf{w}_4 & \mathbf{w}_9 & \mathbf{w}_{10} \\ \mathbf{w}_7 & \mathbf{w}_8 & \mathbf{w}_{11} & \mathbf{w}_{12} \end{bmatrix} \begin{bmatrix} a_2^x \\ a_4^x \\ a_2^y \\ a_4^y \end{bmatrix} = \begin{bmatrix} J_{xl1}^{in} + J_{xr1}^{in} \\ J_{xl2}^{in} + J_{xr2}^{in} \\ J_{yl1}^{in} + J_{yr1}^{in} \\ J_{yl2}^{in} + J_{yr2}^{in} \end{bmatrix} + \begin{bmatrix} f_{b2}(\bar{L}_{z1}, b_{21}^x, b_{21}^y) \\ f_{b2}(\bar{L}_{z2}, b_{22}^x, b_{22}^y) \\ f_{b2}(\bar{L}_{z1}, b_{21}^x, b_{21}^y) \\ f_{b2}(\bar{L}_{z2}, b_{22}^x, b_{22}^y) \end{bmatrix} \quad (16)$$

4x4 . (14)

가

$$J_{out} = RJ_{in} , \quad \bar{\mathbf{f}} = \Phi J_{in} , \quad (17)$$

$J_{in}$  8 (4 x 2 ) ,  $R$  8x8 ,  $\Phi$  2x8

3.

CMFD

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가

### 3.1

(17)

$$J = J_{out|L}^r - J_{out|R}^l \quad (18)$$

$$J_{out|L}^r \quad (L) \quad (r) \quad J_{out|R}^l$$

(R) (l) CMFD

$$J = -\tilde{D}(\bar{\mathbf{f}}_R - \bar{\mathbf{f}}_L) - \hat{D}(\bar{\mathbf{f}}_R + \bar{\mathbf{f}}_L) \quad (19)$$

(17)

$$\hat{D} = \frac{J_{out|L}^r - J_{out|R}^l - \tilde{D}(\bar{\mathbf{f}}_R - \bar{\mathbf{f}}_L)}{\bar{\mathbf{f}}_R + \bar{\mathbf{f}}_L} \quad (20)$$

CMFD (20)

CMFD

가

$$\mathbf{f}_s = \mathbf{a}\bar{\mathbf{f}}_R + (1-\mathbf{a})\bar{\mathbf{f}}_L + \mathbf{b}(\bar{\mathbf{f}}_R + \bar{\mathbf{f}}_L) \quad (20)$$

**a**

FDM

가

가 **b**가

가

**b** (20)

$$\mathbf{b} = \frac{2(J_{out|L}^r + J_{out|R}^l) - \mathbf{a}\bar{\mathbf{f}}_R - (1-\mathbf{a})\bar{\mathbf{f}}_L}{\bar{\mathbf{f}}_R + \bar{\mathbf{f}}_L} \quad (21)$$

(19)

(20)

CMFD

$$J_{xl}^{in} = \frac{1}{4} f_{xl}^s + \frac{1}{2} J_x^l \quad (22)$$

$$f_{xl}^s \quad \text{CMFD} \quad (20) \quad J_x^l$$

(19)

### 3.2

CMFD

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4

CMFD

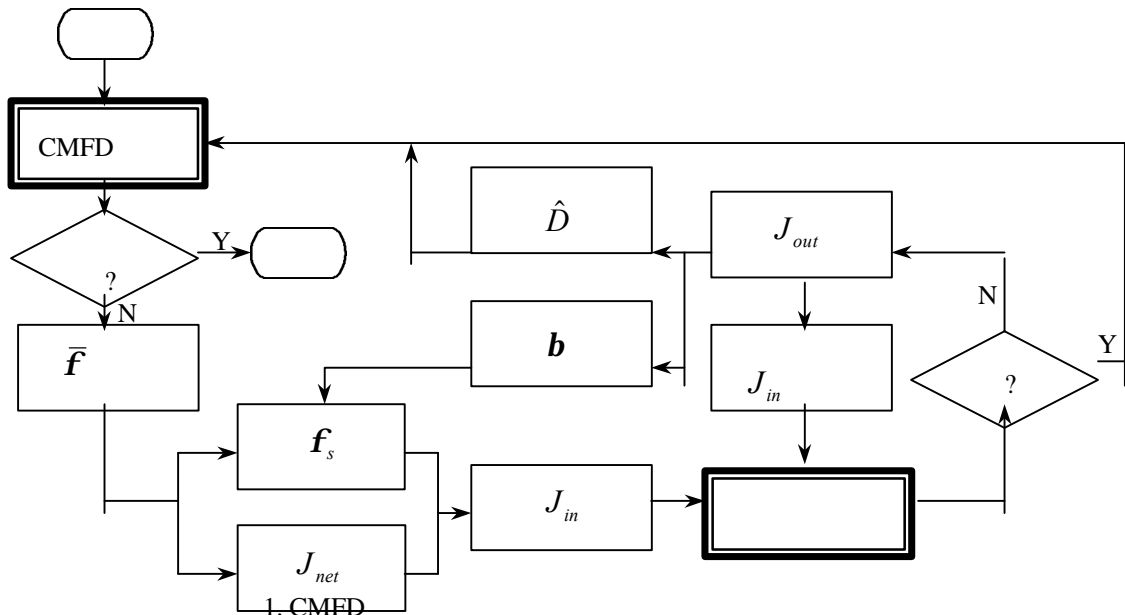
Gauss-Seidel

4

CMFD

Jacobi

4



4.

가



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5

NEACRP A1

[6]

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2

Jacobi

가

Gauss-Seidel

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3

가

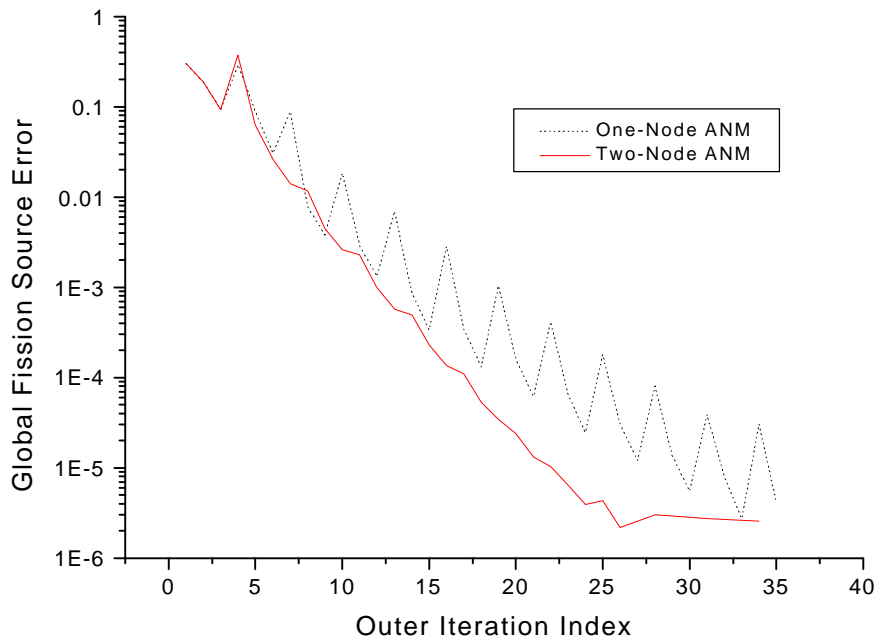
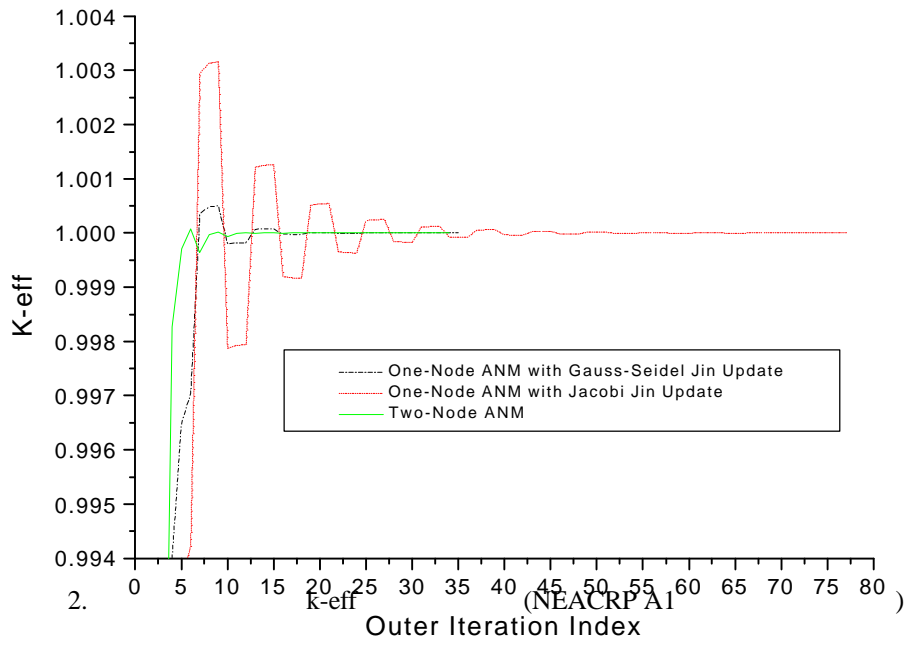
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5.



3. (NEACRP A1 )

1.

	2-Node	1-Node	2-Node	1-Node
(ppm) / (%)	561.7	561.7	125.63	125.73
	12	12	40	46
CMFD	36	36	503	551
,	1.14	1.09	3.51	3.71
,	7.8		61.1	

Gauss-Seidel

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