

MARS 3

**Implementation of shear stresses and 3 dimensional momentum convection term into MARS code and an analysis of effects on the two phase fluid flow**

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TRAC, RELAP5-3D, CATHARE

MARS 3

. MARS

RELAP5/MOD3

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COBRA-TF

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**Abstract**

*Not only the main and lateral momentum convection term but also the shear stress term should be considered in the momentum equations for the calculation of full three dimensional flow field of two phase flow. Some of the thermal-hydraulic system codes such as TRAC, RELAP5-3D and CATHARE have been developed for the analysis of 3D field calculations by considering the full 3D momentum convection*

terms. The 3D module of MARS code also has the feature of 3D flow calculation of turbulence mixing model. The MARS code consists of 1D module which has been developed from RELAP5/MOD3 and 3D module which has been developed from COBRA-TF. Since the 1D and 3D module of MARS use the different set of interfacial correlations and field equation, it has a limited capability to the analysis of the separated 3D flow effect. The 3D momentum convection term and shear stress term have been implemented for MARS 1D module in order to extend its capability of 3D flow field calculation. Verification calculations of MARS implementation have been performed for the simple geometry of the slab downcomer and core. The effect on the single and two phase flow field has been discussed also.

**1.**

		3			
TRAC[1]	VESSEL Component	1980		3	
가	CATHRE[2,3]	CATHARE-2 v1.4	3		가
	RELAP5[4]	1990	NRC	1	
RELAP5/MOD3.2		RELAP5-3D[5]			COBRA-TF
	COBRA		2	3	
	COBRA-TF	TRAC		COBRA/TRAC[6]	3
LOCA		Westinghouse 가			
	MARS[7]	1	RELAP5/MOD3	COBRA-TF	
		3			
		3	가		
			FLUENT	CFX	
					LOCA
					가
				MARS	3
		3			

**2. MARS**

**3**

MARS

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$$\frac{\partial}{\partial t}(\alpha_g \rho_g) + \frac{1}{A} \frac{\partial}{\partial x}(\alpha_g \rho_g u_g A) = \Gamma_g \quad (1)$$

$$\frac{\partial}{\partial t}(\alpha_f \rho_f) + \frac{1}{A} \frac{\partial}{\partial x}(\alpha_f \rho_f u_f A) = \Gamma_f \quad (2)$$


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$$\begin{aligned} \alpha_g \rho_g A \frac{\partial u_g}{\partial t} + \frac{1}{2} \alpha_g \rho_g A \frac{\partial u_g^2}{\partial x^2} = & -\alpha_g A \frac{\partial P}{\partial x} + \alpha_g \rho_g B_x A - (\alpha_g \rho_g A) F W G(u_g) + \Gamma_g A (u_{g,I} - u_g) \\ & - (\alpha_g \rho_g A) F I G(u_g - u_f) - C \alpha_g \alpha_f \rho_m A \left[ \frac{\partial (u_g - u_f)}{\partial t} + u_f \frac{\partial u_g}{\partial x} - u_g \frac{\partial u_f}{\partial x} \right] \end{aligned} \quad (3)$$

$$\begin{aligned} \alpha_f \rho_f A \frac{\partial u_f}{\partial t} + \frac{1}{2} \alpha_f \rho_f A \frac{\partial u_f^2}{\partial x^2} = & -\alpha_f A \frac{\partial P}{\partial x} + \alpha_f \rho_f B_x A - (\alpha_f \rho_f A) F W F(u_f) - \Gamma_g A (u_{f,I} - u_f) \\ & - (\alpha_f \rho_f A) F I F(u_f - u_g) - C \alpha_g \alpha_f \rho_m A \left[ \frac{\partial (u_f - u_g)}{\partial t} + u_g \frac{\partial u_f}{\partial x} - u_f \frac{\partial u_g}{\partial x} \right] \end{aligned} \quad (4)$$

$$\frac{\partial}{\partial t}(\alpha_g \rho_g) + \frac{1}{A_x} \frac{\partial}{\partial x}(\alpha_g \rho_g u_g A_x) + \frac{1}{A_y} \frac{\partial}{\partial y}(\alpha_g \rho_g v_g A_y) + \frac{1}{A_z} \frac{\partial}{\partial z}(\alpha_g \rho_g w_g A_z) = \Gamma_g \quad (5)$$

$$\frac{\partial}{\partial t}(\alpha_f \rho_f) + \frac{1}{A_x} \frac{\partial}{\partial x}(\alpha_f \rho_f u_f A_x) + \frac{1}{A_y} \frac{\partial}{\partial y}(\alpha_f \rho_f v_f A_y) + \frac{1}{A_z} \frac{\partial}{\partial z}(\alpha_f \rho_f w_f A_z) = \Gamma_f$$

$$\rho \left( \frac{\partial \vec{V}}{\partial t} + \vec{V} \cdot \nabla \vec{V} \right) = -\nabla P + \vec{\sigma} + \rho \vec{f} \quad (6)$$

$$\begin{aligned} \vec{V} \cdot \nabla \vec{V} &= u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} : x\text{-component} \\ &= u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} : y\text{-component} \\ &= u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} : z\text{-component} \end{aligned} \quad (7)$$

$$\begin{aligned} \vec{V} \cdot \nabla \vec{V} &= u \frac{\partial u}{\partial r} + \frac{v}{r} \frac{\partial u}{\partial \theta} + w \frac{\partial u}{\partial z} - \frac{v^2}{r} : r\text{-component} \\ &= u \frac{\partial v}{\partial r} + \frac{v}{r} \frac{\partial v}{\partial \theta} + w \frac{\partial v}{\partial z} + \frac{uv}{r} : \theta\text{-component} \\ &= u \frac{\partial w}{\partial r} + \frac{v}{r} \frac{\partial w}{\partial \theta} + w \frac{\partial w}{\partial z} : z\text{-component} \end{aligned} \quad (8)$$

x

$$\begin{aligned} &\alpha_g \rho_g A \frac{\partial u_g}{\partial t} + \frac{1}{2} \alpha_g \rho_g A \frac{\partial u_g^2}{\partial x} + \alpha_g \rho_g A v_g \frac{\partial u_g}{\partial y} + \alpha_g \rho_g A w_g \frac{\partial u_g}{\partial z} = \\ &-\alpha_g A \frac{\partial P}{\partial x} + \alpha_g \rho_g B_x A - \alpha_g \rho_g A (FWG) u_g + \Gamma_g A (u_{gt} - u_g) - \alpha_g \rho_g A (FIG) (u_g - u_f) \\ &- C \alpha_g \alpha_f \rho_m A \left[ \frac{\partial (u_g - u_f)}{\partial t} + u_f \frac{\partial u_g}{\partial x} - u_g \frac{\partial u_f}{\partial x} \right] + \alpha_g A (\mu_g + \mu_{g,r}) \left[ \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right] \end{aligned} \quad (9)$$



$$\begin{aligned}
& (\alpha_g \rho_g)_{j,k,l}^n (u_g^{n+1} - u_g^n)_{j,k,l} \Delta x_{j,k,l} + \frac{1}{2} (\alpha_g^* \rho_g^*)_{j,k,l}^n \left[ (u_g^2)_L^n - (u_g^2)_K^n \right] \Delta t - \frac{1}{2} \left[ (\alpha_g^* \rho_g^*)_{j,k,l}^n \text{VISG}_{j,k,l}^n \right] \Delta t \\
& + \frac{1}{2} \left[ (\alpha_g^* \rho_g^*)_{j,k,l+1}^n (u_g^*)_{j,k,l+1}^n (v_{g,j,k,l+1}^n + v_{g,j-1,k,l+1}^n) - (\alpha_g^* \rho_g^*)_{j,k,l}^n (u_g^*)_{j,k,l}^n (v_{g,j,k,l}^n + v_{g,j-1,k,l}^n) \right] \frac{\Delta x_{j,k,l}}{\Delta y_{j,k,l}} \Delta t \\
& + \frac{1}{2} \left[ (\alpha_g^* \rho_g^*)_{j,k,l+1}^n (u_g^*)_{j,k,l+1}^n (w_{g,j,k,l+1}^n + w_{g,j-1,k,l+1}^n) - (\alpha_g^* \rho_g^*)_{j,k,l}^n (u_g^*)_{j,k,l}^n (w_{g,j,k,l}^n + w_{g,j-1,k,l}^n) \right] \frac{\Delta x_{j,k,l}}{\Delta z_{j,k,l}} \Delta t \\
& = -(P_L - P_K)^{n+1} \Delta t + \left[ (\alpha_g \rho_g)_{j,k,l}^n g - (\alpha_g \rho_g)_{j,k,l}^n \text{FWG}_{j,k,l}^n u_g^{n+1} - (\Gamma_g)_{j,k,l}^n (u_g - u_{g,l})_{j,k,l}^{n+1} \right] \Delta x_{j,k,l} \Delta t \\
& - \left[ (\alpha_g \rho_g)_{j,k,l}^n \text{HLOSSG}_{j,k,l}^n u_{g,j,k,l}^{n+1} \right] \Delta t \\
& - (\alpha_g \rho_g)_{j,k,l}^n (\mu_g + \mu_{g,T})_{j,k,l}^n \left[ (u_{g,j,k,l+1}^n - u_{g,j,k,l}^n) \frac{1}{\Delta y_{j,k,l+1}} - (u_{g,j,k,l}^n - u_{g,j,k-1,l}^n) \frac{1}{\Delta y_{j,k,l}} \right] \frac{\Delta x_{j,k,l}}{\Delta y_{j,k,l}} \Delta t \\
& - (\alpha_g)_{j,k,l}^n (\mu_g + \mu_{g,T})_{j,k,l}^n \left[ (u_{g,j,k,l+1}^n - u_{g,j,k,l}^n) \frac{1}{\Delta z_{j,k,l+1}} - (u_{g,j,k,l}^n - u_{g,j,l-1}^n) \frac{1}{\Delta z_{j,k,l}} \right] \frac{\Delta x_{j,k,l}}{\Delta z_{j,k,l}} \Delta t
\end{aligned}$$

x

x-y-z

6

explicit

Courant

diffusion

explicit

가

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MARS

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### 3. 3

### MARS

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MARS

INEEL

RELAP5-3D

USNRC RELAP5/MOD3

, roughness,

3

3

x-y-z

K

L

가 junction

3

K

, L

, j junction

6

junction

가

6

가 vface(6), jface(6)

junction

가 jface(6)

---

```

MODULE VOL_DAT
  TYPE VOLUME_HEADER
    INTEGER nvols(2)
  END TYPE
  TYPE VOLUME_DATA; SEQUENCE
.
.
. ( )
.
.
  INTEGER vface(6),jface(6)
END TYPE
TYPE(VOLUME_HEADER)          :: v_hd
TYPE(VOLUME_DATA), ALLOCATABLE :: v_da(:),v_dax(:)
END MODULE VOL_DAT

```

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```

MODULE JUN_DAT
  TYPE JUNCTION_HEADER
    INTEGER njuns(2)
  END TYPE
  TYPE JUNCTION_DATA ; SEQUENCE
    INTEGER ij1(2),ij2(2),ij1vn(2),ij2vn(2),junftl(2,2)
    INTEGER jface(6)
.
.
. ( )
.
.
  END TYPE
  TYPE(JUNCTION_HEADER)          :: j_hd
  TYPE(JUNCTION_DATA),ALLOCATABLE :: j_da(:), j_dax(:)
END MODULE JUN_DAT

```

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MARS      VEXPLT                                explicit
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67        ,                                     68
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#### 4. MARS

2D 3D MARS

##### 4.1 2D

APR1400

가

water

film ( ) 1

가

1) 1 50 m/sec

2) 2 1 m/sec water film

3) 3 1) 1m/sec water film

4) 4 1)

2 3 junction x-y-z 6 2 9 cross flow 3

1) Option 1

y- cross flow junction momentum flux term

)

\*\*\*\*\*

\*\* Cross Flow Junction of the lower annulus

1500000	to_200	mtpljun						
1500001	9	1						
1500011	100010004	200010003	0.10000	0.0	0.0	000003		
1500012	1.0	1.0	1.0					
1500013	10000	10000	0	9				
1501011	0.0	0.0	9					
1502011	0.00000	0.0	1.0	1.0	9			

2) Option 2

y- cross flow junction momentum flux term

)



fraction 0.9 ~ 1.0

r- momentum flux 가 water film 가  
, 3 momentum flux film 2 film  
가 film 가

3) 3 : Water film Bypass

1) water film water film  
2) bypass 5 film Option 1  
가 bypass 가 . Option 3 3  
momentum flux 가

4) 4 :

6  
3 momentum flux 가  
. Full momentum flux  
가

#### 4.2 3D

가 7 5 x 5 25  
9 가 225  
가 flow 가 가

exit  
8 9 full momentum flux option

continuity

8 cross flow momentum flux  
10 11 3D momentum flux option 2  
Turbulence shear 11 shear  
force 2

5.

3

momentum flux

3

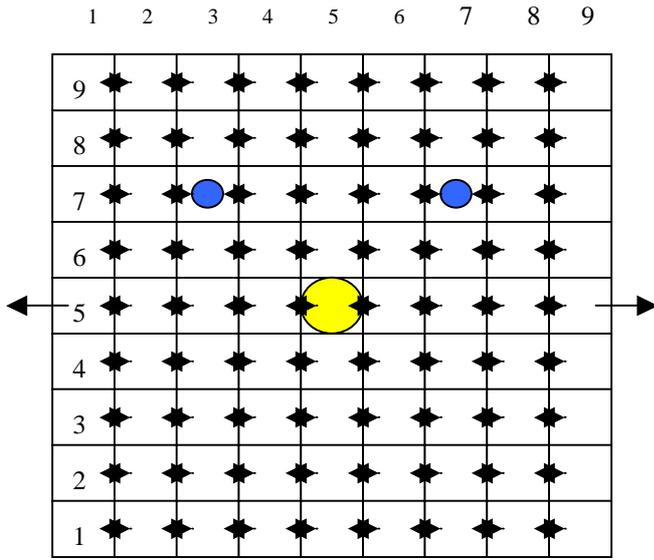
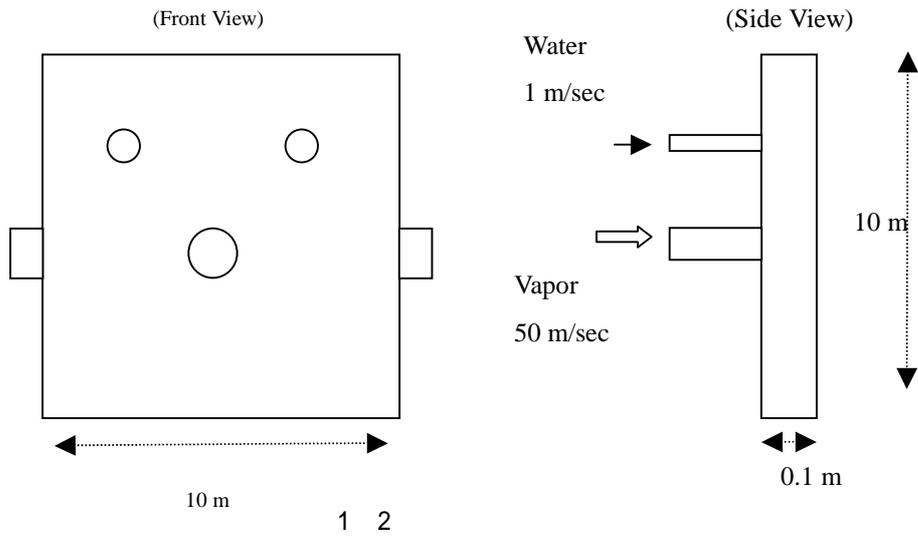
r- $\theta$ -z

explicit

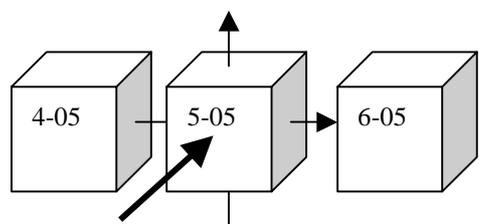
3 component

6.

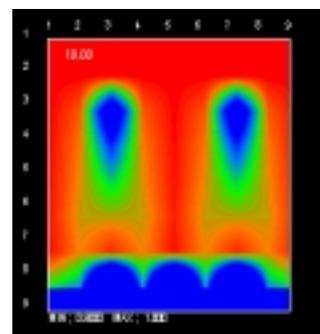
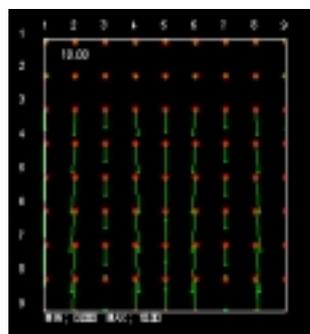
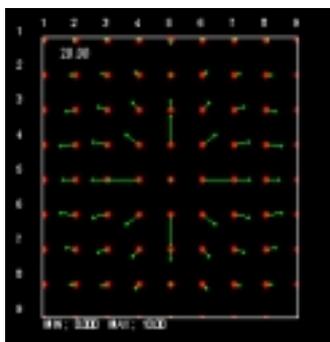
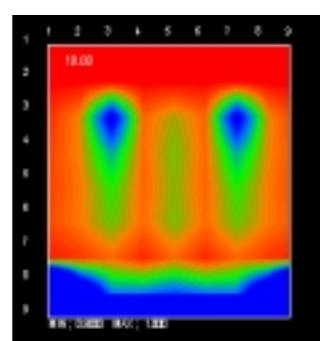
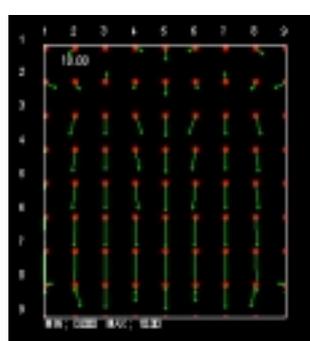
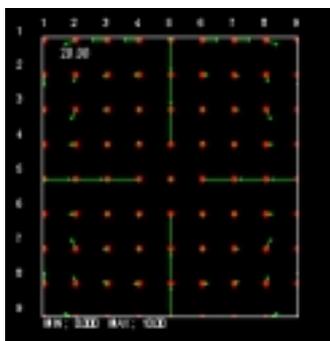
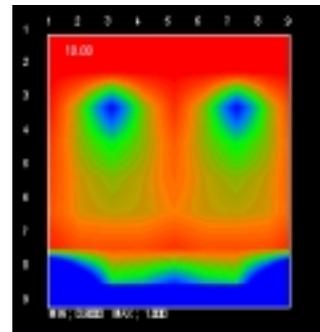
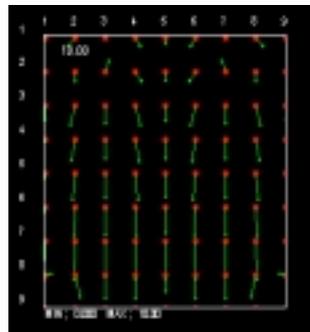
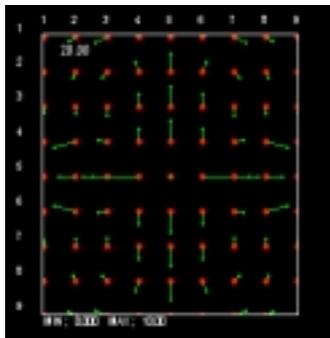
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- [2] D. Bestion “The Physical Closure Law in the CATHARE Code”, Nuclear Science and Design, Vol. 124 , pp 229-245 (1990)
- [3] F. Barre and M. Bernard, “The CATHARE code strategy and assessment”, Nuclear Science and Design, Vol. 124, pp 257-284 (1990)
- [4] Thermal Hydraulics Group “RELAP5/MOD3 Code Manual Volume 4 : Models and Correlations”, page 3-9, Scientech, Inc. , NUREG/CR-5535 (1998)
- [5] The RELAP5-3D Code Development Team, RELAP5-3D Code Manual Volume 1, Code Structure, System Models and Solution Methods, INEEL-EXT-98-00834 Revision 1.1b, July (1999)
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- [7] W.J.Lee, B.D.Chung, J.J.Jeong, and K.S.Ha, “Development of a Multi-Dimensional Realistic Thermal-Hydraulic System Analysis Code, MARS1.3 and Its Verification”, KAERI/TR-1108/98 (1998)



MARS 2D Nodalization of Slab

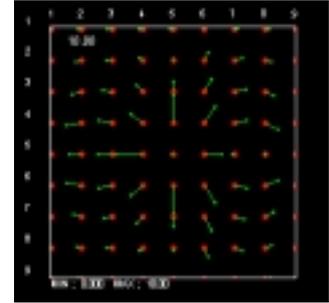
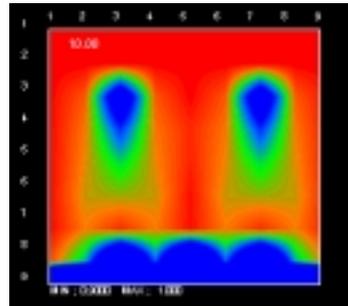
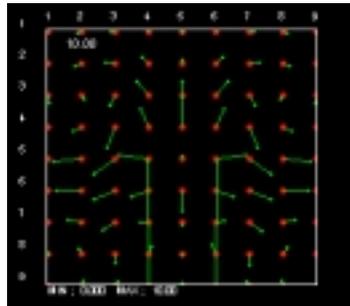
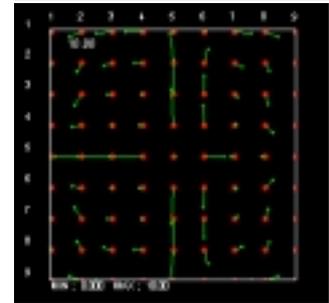
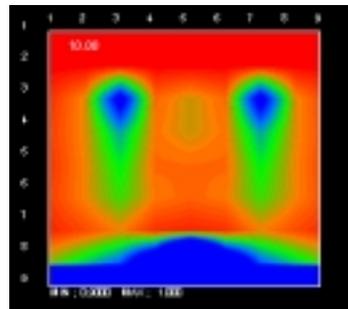
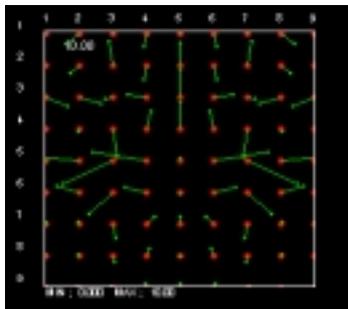
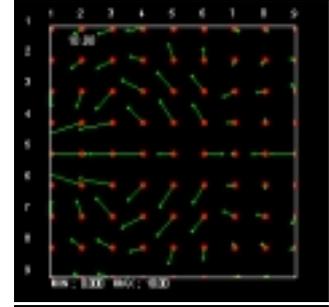
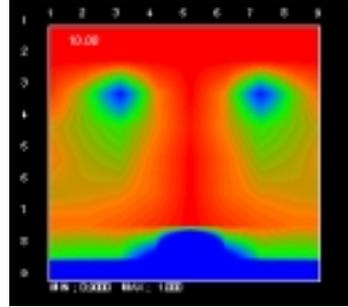
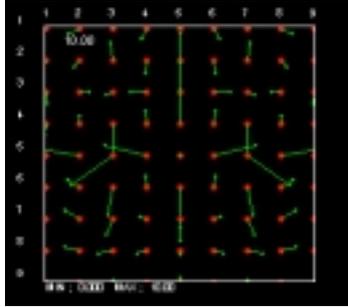


RELAP5 3D Nodalization of 5-05



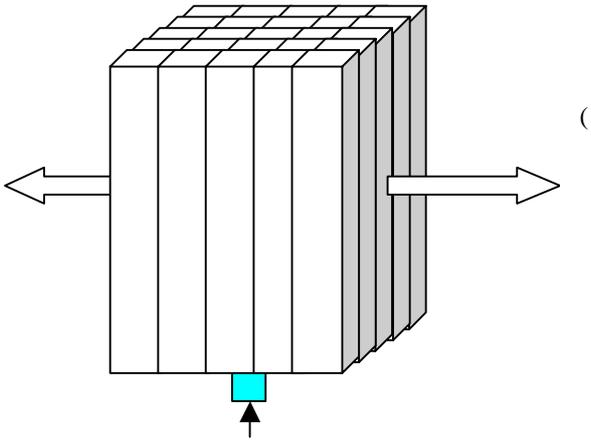
3 50 m/sec  
 (Top; No r-direction momentum flux  
 Mid; r-z main direction momentum flux  
 Bottom; full momentum flux )

4 1 m/sec water film  
 (Top; No r-direction momentum flux  
 Mid; r-z main direction momentum flux  
 Bottom; full momentum flux )



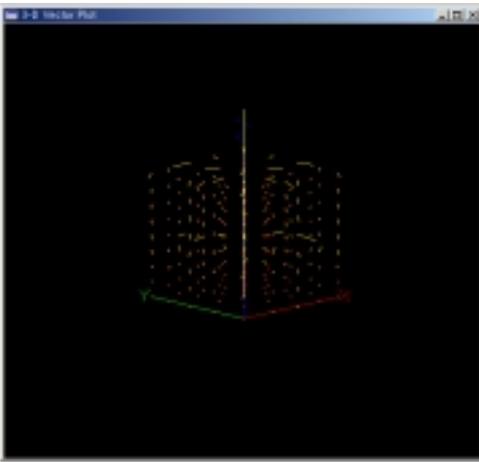
5 water film  
 (Top; No r-direction momentum flux  
 Mid; r-z main direction momentum flux  
 Bottom; full momentum flux )

6 Hot leg resistance 가  
 (Top; No r-direction momentum flux  
 Mid; r-z main direction momentum flux  
 Bottom; full momentum flux )

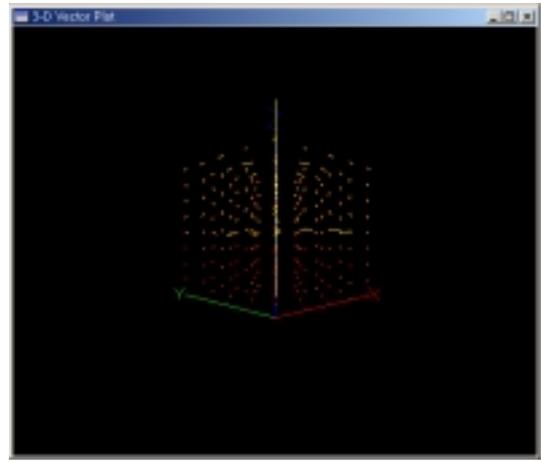


7. 3

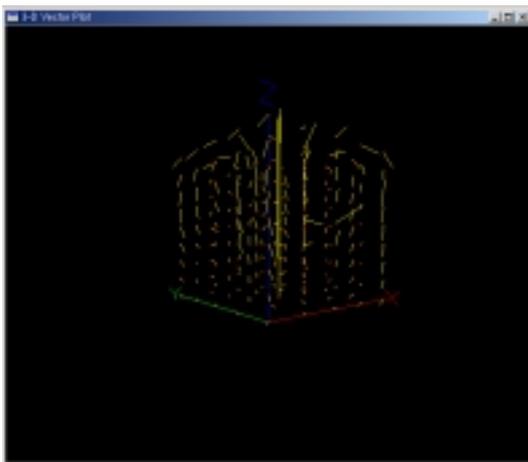
( 가 가 2 )



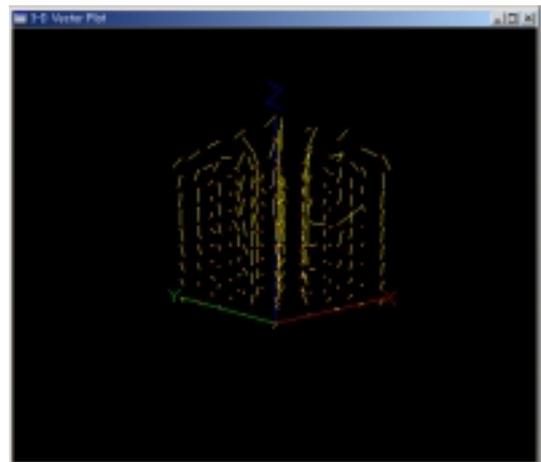
8. main direction momentum flux



9. cross flow momentum flux



10. 3 full momentum flux term



11. 3 full momentum flux turbulence shear